Resets the gyro sensor

Turns the right wheel, which makes the robot turn left

Makes the robot turn left 5 degrees

The robot goes forward for 1.5 seconds and hits the wall

The robot goes backward for a set number of rotations.

Turns the right wheel, which makes the robot turn left

Makes the robot turn 110 degrees to the left.

Resets the gyro sensor

Moves forward for a set amount of rotations and hits the elevator.

Goes forward until a wait block

Makes the robot move